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/*File will not run without the Constrained Optimization Module obtainable
at www.aptech.com*/
/*Settings for Constrained Optimization*/
new;
library co;
screen on;
coset;
format /M1 /ROS 16,5;
cls;
_co_Algorithm = 3;
_co_LineSearch = 2;
_co_Bounds = { 0 1 };
_co_MaxIters = 10000;
_co_DirTol = 3*1e-5;

/*Necessary Input: P= Vector of Interst Positions; R= Vector of Actors' Power;
Vector containing informaiton on the kind of actor 1= non-state, 2=state, 3=leading
ministry*/

P = {0.1, 0.4, 0.3, 0.5, 0.8, 1, 1 };
R = {0.2, 0.2, 1, 1, 1, 0.3, 0.3 };
K = { 1,1,2,2,3,1,1 };

/*Set a = 1 for asymmetric version*/
a= 0;
/*****/

/*Relative Power*/
R = R./sumc(R);

/*Selecting Actors for Clientelistic Model*/
PRK = zeros(rows(P),3);
PRK[1:rows(P), 1] = P;
PRK[1:rows(P), 2] = R;
PRK[1:rows(P), 3] = K;
sortc(PRK, 1);
lim = abs(PRK[1,1]-PRK[rows(P),1])/3;
i=1;
lm = 0;
do while i<= rows(PRK);
if PRK[i,3] == 3;
lm = i;
endif;
i = i+1;
endo;

TT = zeros(rows(P),3);
i = 1;
h = 1;
do while i <= rows(P);
if PRK[i,1] >= PRK[lm,1]-lim and PRK[i,1] <= PRK[lm,1]+lim;
TT[h, 1:3] = PRK[i, 1:3];

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h = h+1;
endif;
i = i+1;
endo;
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```
P = TT[1:h-1, 1];
R = TT[1:h-1, 2];
K = TT[1:h-1, 3];
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/*Defining the Disagreement Value D*/
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D = zeros(rows(P),1);
i = 1;
do while i <= rows(P);
if P[i,1] > 0.5;
D[i,1] = (1-R[i,1])*P[i,1];
endif;
if P[i,1] <= 0.5;
D[i,1] = (1-R[i,1])*(1-P[i,1]);
endif;
i = i+1;
endo;
```

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/*Constraining the possible outcome on pareto efficiency*/
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proc dumm(x);
local nc;
nc = D-abs(P-x);
retp(minc(nc)-1e-5);
endp;
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/*Setting the Starting Vector on the Mean Position*/
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x0 = meanc(P);
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/*Activation of CO-procedure and constraint*/
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_co_IneqProc = &dumm;
{x, f, g, retcode } = co(&fsys, x0) ;
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/*Procedure containing the utility functions for NBS*/
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```
if a==0;
R = 1+zeros(rows(R),1);
endif;
/*Relative Power*/
R = R./sumc(R);
proc fsys(x);
local uf, er;
uf = (D-abs(P-x[1])).^R;
er = prodc(uf);
retp(-1*er);
endp;
call coPRT(x, f,g,retcode);
```

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/*Return predicted Outcome!*/
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print x;
```